

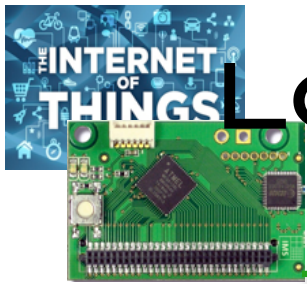
INVESTIGATING AND EXPERIMENTING CSMA CHANNEL ACCESS MECHANISMS FOR LORA IOT NETWORKS

IEEE WCNC 2018 CONFERENCE
BARCELONA, SPAIN, APRIL 16TH, 2018



PROF. CONGDUC PHAM
[HTTP://WWW.UNIV-PAU.FR/~CPHAM](http://www.univ-pau.fr/~cpham)
UNIVERSITÉ DE PAU, FRANCE

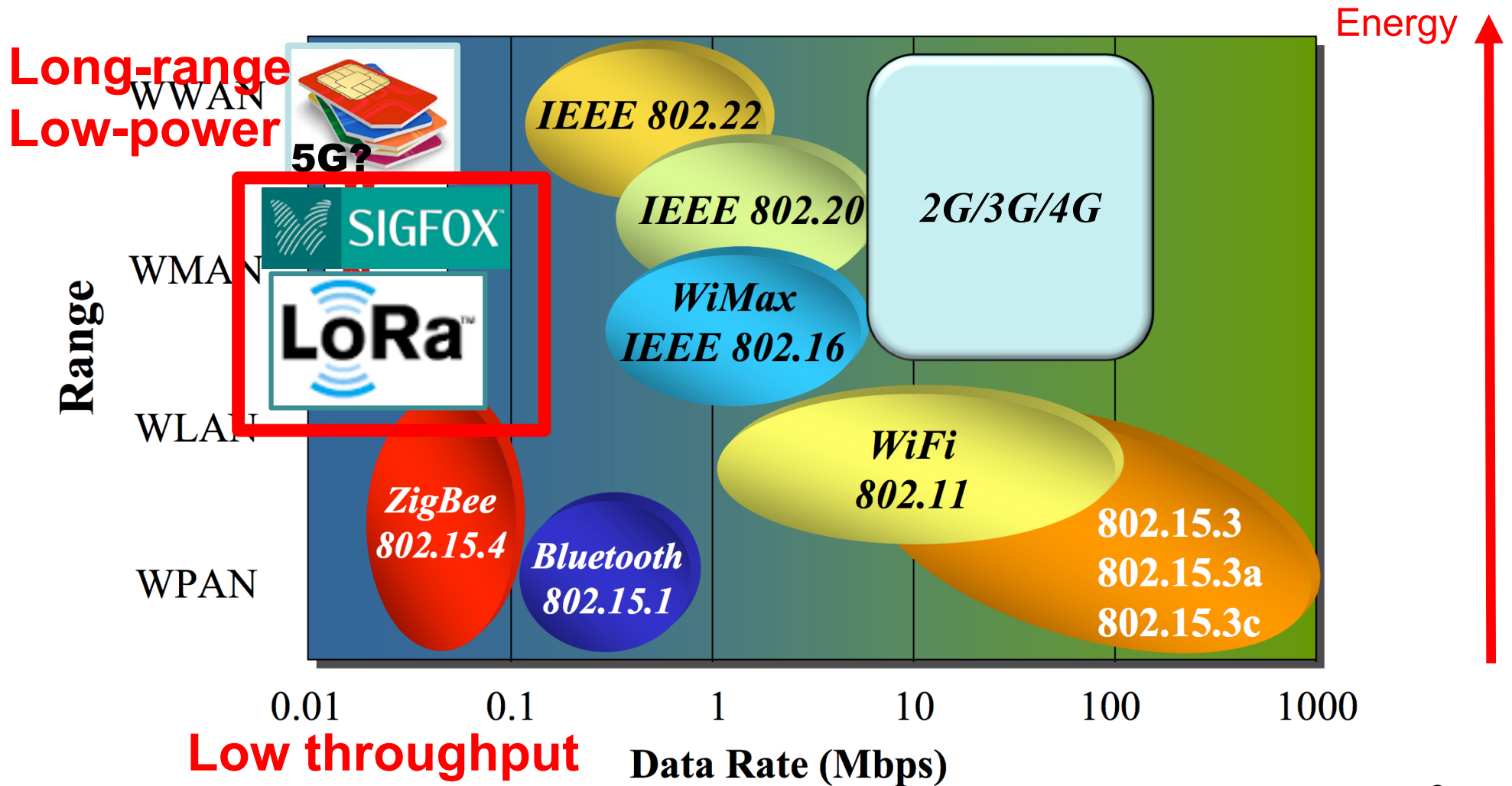


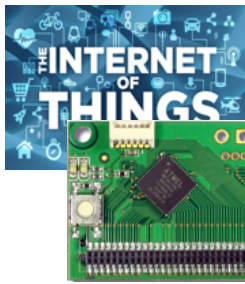


LOW-POWER & LONG-RANGE RADIO TECHNOLOGIES



Energy-Range dilemma





ROBUST CHANNEL ACCESS MECHANISMS



- LoRa networks will get densier with a large variety of devices and data traffic profiles

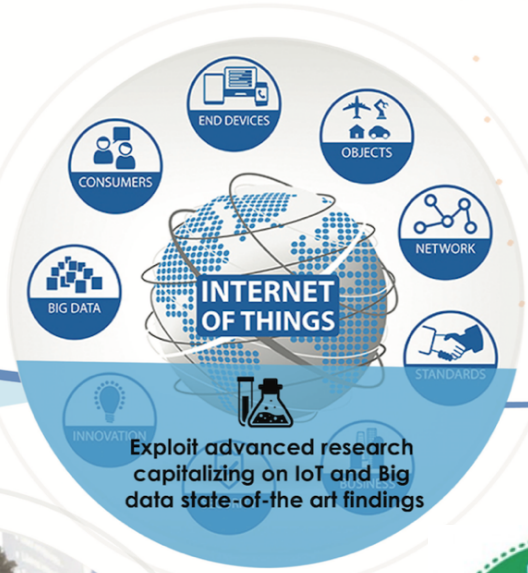
- Traditional simple sensor
→ small messages
- Traditional multi-sensor
→ medium messages
- Innovative image sensors
→ large messages
→ Time on Air can be of several seconds!

LoRa mode	BW (kHz)	SF	time on air in second for payload size of					max throughput in bps	
			5 bytes	55 bytes	105 bytes	155 Bytes	205 Bytes		255 Bytes
1	125	12	0.9585	2.5969	4.2353	5.8737	7.5121	9.1505	223
2	250	12	0.4792	1.2165	1.8719	2.5272	3.2645	3.9199	520
3	125	10	0.2806	0.6902	1.0998	1.5094	1.919	2.3286	876
4	500	12	0.2396	0.6083	0.9359	1.2636	1.6323	1.9599	1041
5	250	10	0.1403	0.3451	0.5499	0.7547	0.9595	1.1643	1752
6	500	11	0.1198	0.3041	0.5089	0.6932	0.8776	1.0619	1921
7	250	9	0.0701	0.1828	0.2954	0.4081	0.5207	0.6333	3221
8	500	9	0.0351	0.0914	0.1477	0.204	0.2604	0.3167	6442
9	500	8	0.0175	0.0508	0.0815	0.1148	0.1455	0.1788	11408
10	500	7	0.0088	0.028	0.0459	0.0638	0.083	0.1009	20212

- Objectives are to reduce packet collisions, thus reducing delivery latency, and reduce power consumption due to unsuccessful transmissions
- Current raw LoRa networks are mainly pure ALOHA systems
- Some LoRaWAN implementations proposes simple Listen-Before-Talk mechanism



Affordable technologies to empower rural economics



Develop IoT solutions and applications meeting African needs

DO MORE with LESS

- www.waziup.eu
- Waziup IoT
- Waziup IoT
- Waziup
- Waziup



waziup.community@create-net.org



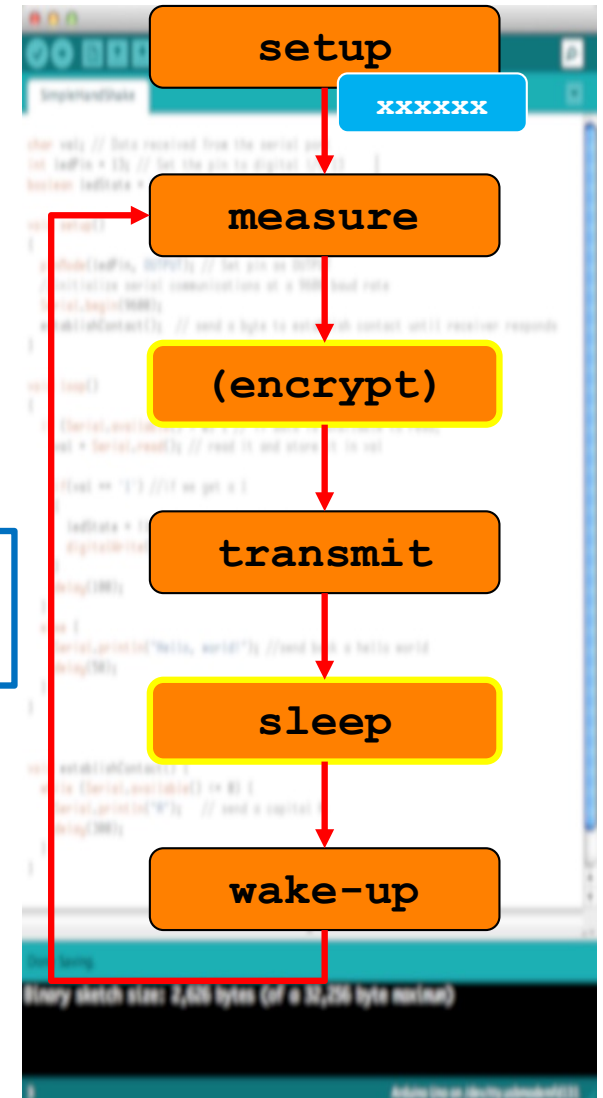
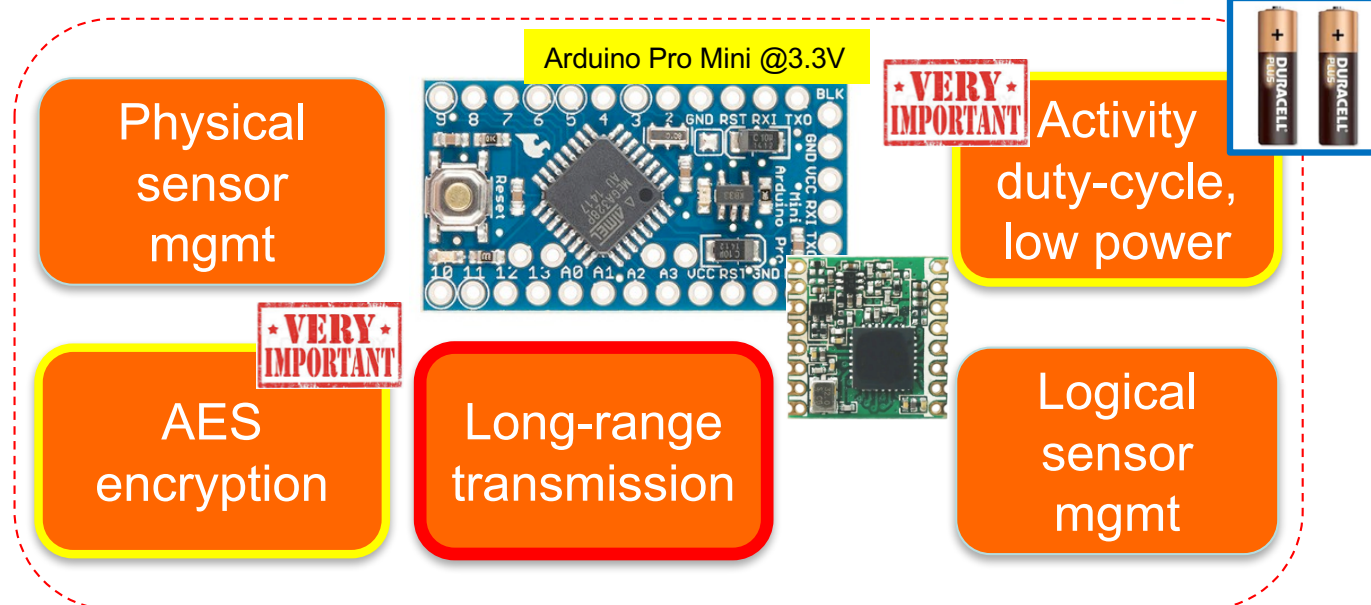
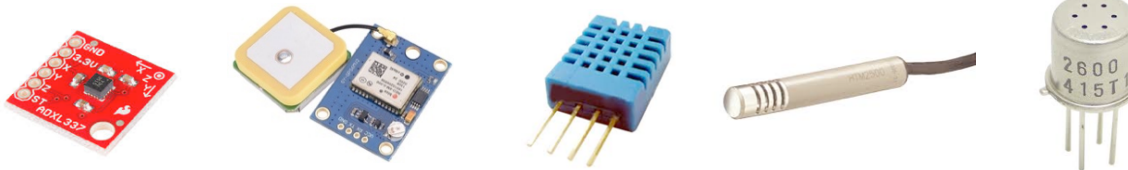
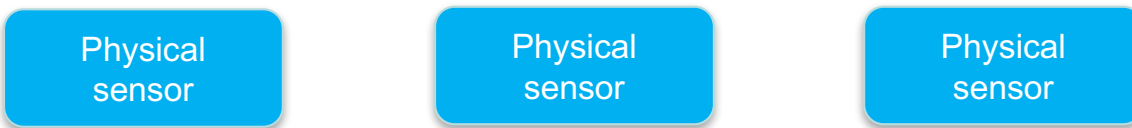
GENERIC LOW-COST IOT DEVICE

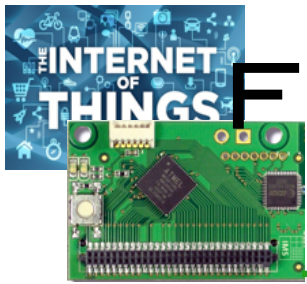


Moisture/
Temperature of
storage areas



10-15kms





FROM GENERIC TO SPECIFIC APPLICATIONS



LARGE MESSAGES

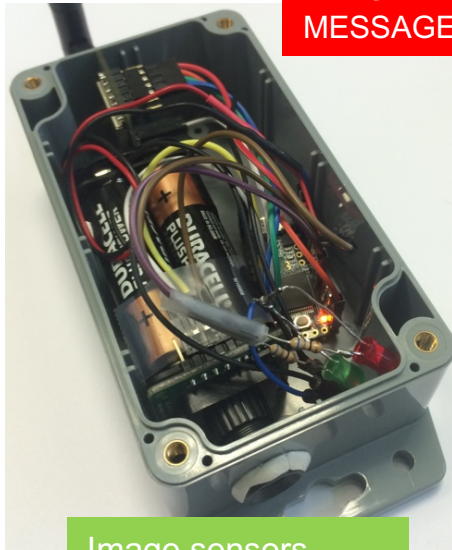
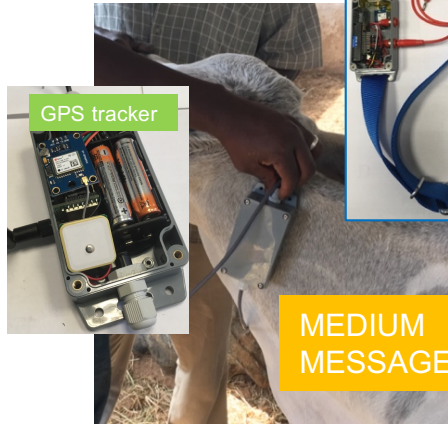
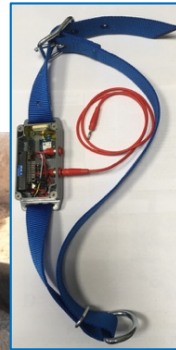


Image sensors

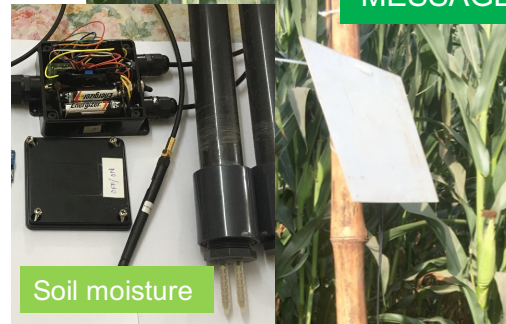
GPS tracker



MEDIUM MESSAGES



SMALL MESSAGES



Soil moisture

MEDIUM MESSAGES



Photo from EGM



Buoy for water quality

MEDIUM MESSAGES



Weather Station

Photo from Unparallel

Bin presented at Woelab



SMALL MESSAGES

Waste Mngt

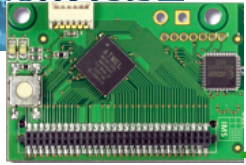
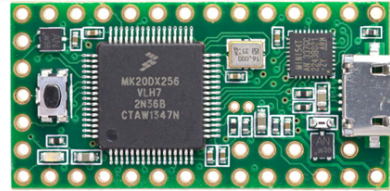
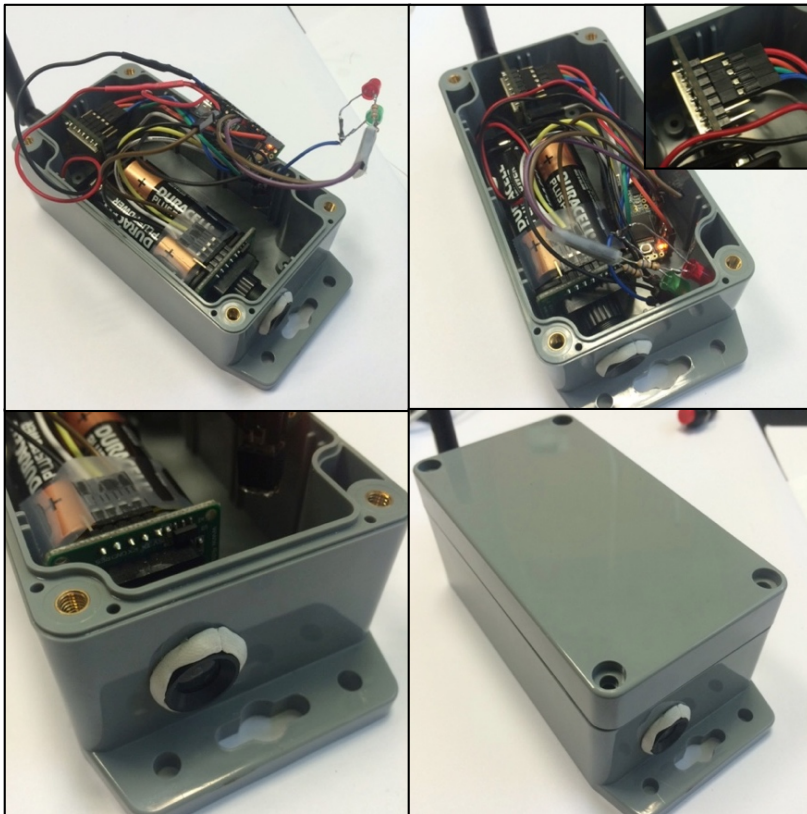


IMAGE SENSOR DEVICE

□ Teensy32



+ uCamII/III



56° lens



76° lens



116° lens



The uCam is shipped with a 56° angle of view lens but 76° and 116° lenses are also available for various application needs.

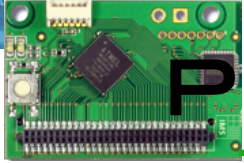


IMAGE ENCODING PERFORMANCES, Q=10 & 20

Quality Factor Q	96MHz		72MHz		48MHz		24MHz		MSS=240	
	encode	packetiza	encode	packetiza	encode	packetiza	encode	packetiza	number of packets	size in bytes (compression ratio)
100								813	47	9982 (1.64)
90								322	23	5090 (3.21)
80								218	16	3595 (4.55)
70								178	13	2842 (5.76)
60								162	11	2461 (6.65)
50								150	10	2129 (7.69)
40								139	9	1898 (8.63)
30	224	33	260	44	345	64	637	127	7	1608 (10.19)
20	223	31	260	39	345	58	636	115	6	1279 (12.81)
10	223	26	260	31	345	50	636	99	4	824 (19.88)
5	223	23	259	31	344	45	635	89	3	503 (32.57)

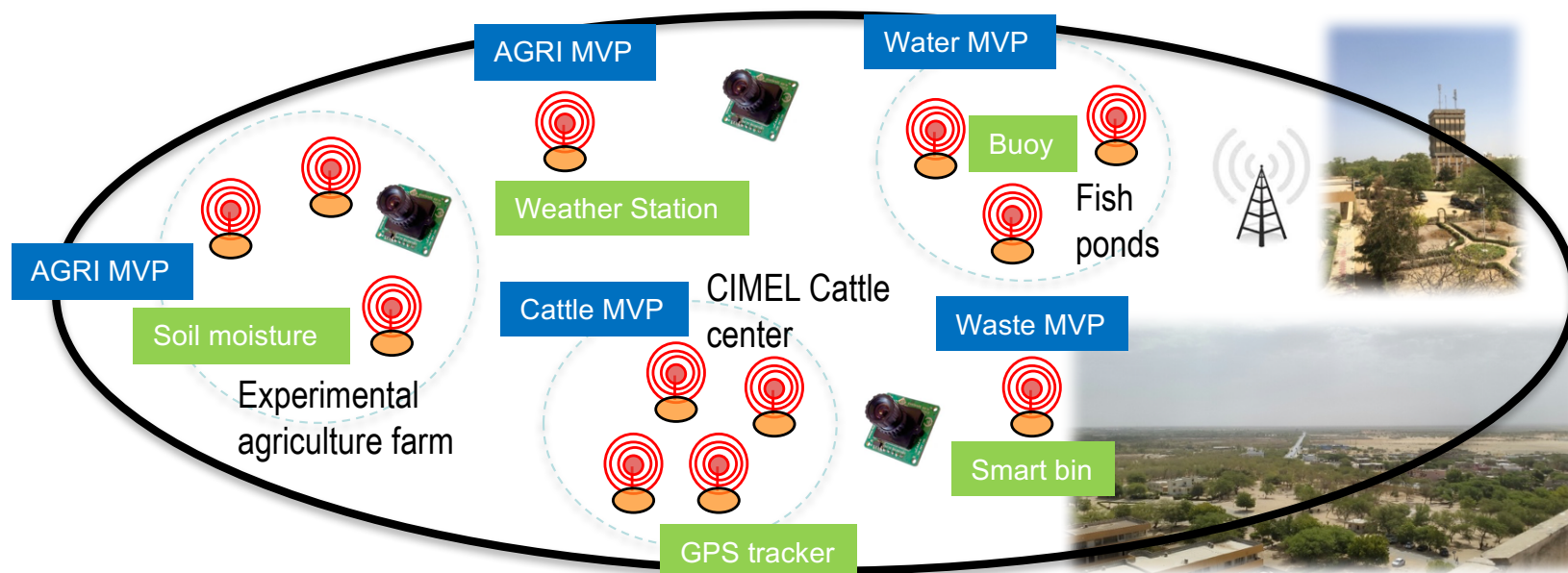
- ❑ Capturing an image and encoding it roughly take 2.3s
 - ❑ Time to sync & config ucam is about 400ms
 - ❑ Time to read raw image data from ucam is 1512ms
 - ❑ Time of compare with reference image is neglectible
 - ❑ Time for encoding and packetization is about 300ms

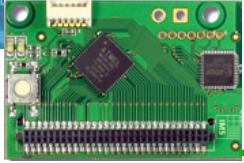


DEPLOYING IN WAZIUP PILOT TEST-BED



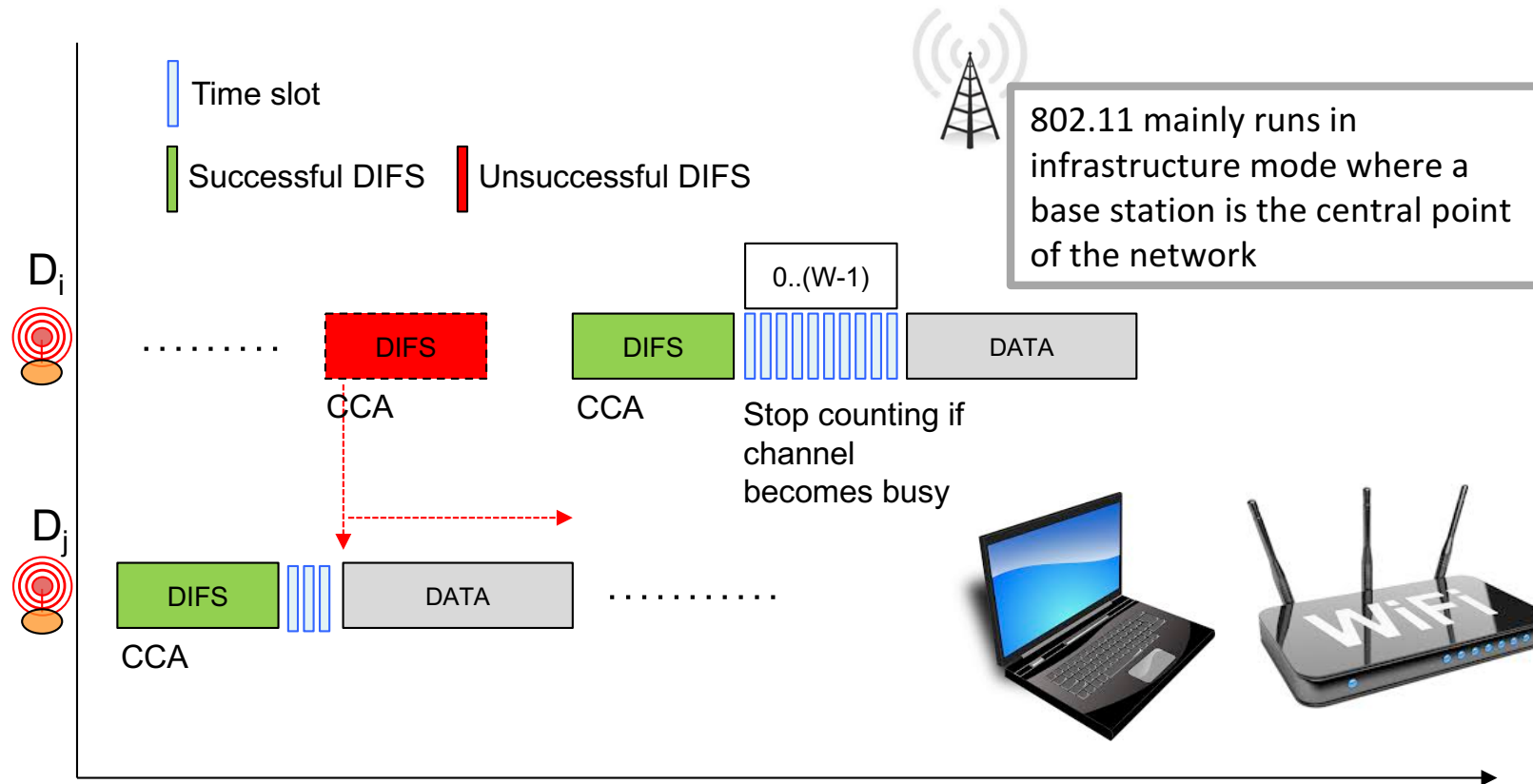
- ❑ Pilot test-bed in Gaston Berger University, Saint-Louis, Senegal, to test all WAZIUP use-cases
- ❑ Gateway placed on top of a 30m-high building





REVIEW OF IEEE 802.11 CSMA/CA

- DIFS, SIFS
- Random backoff [0..W[

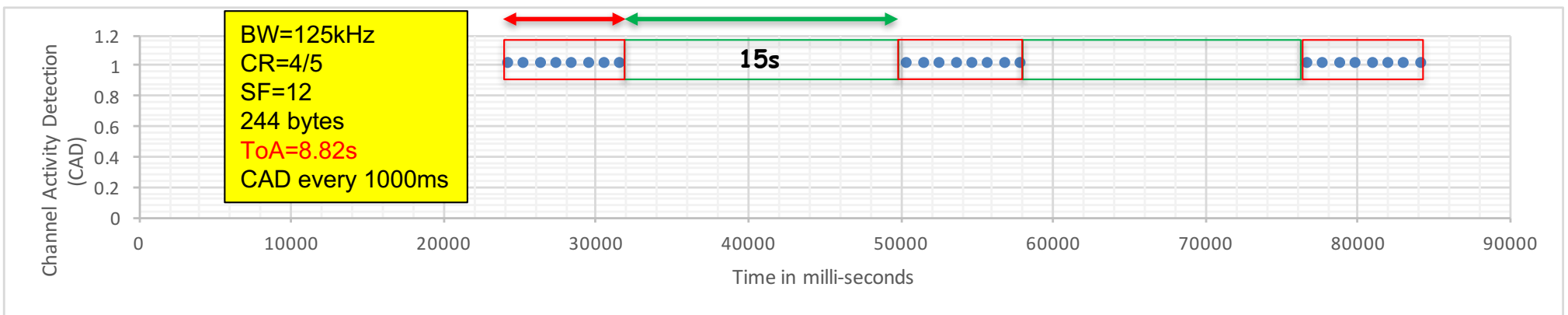
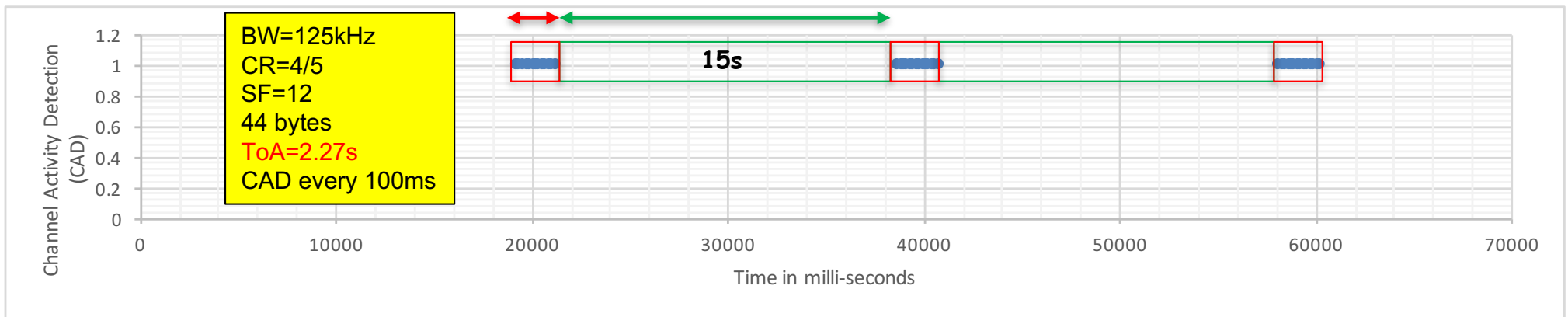


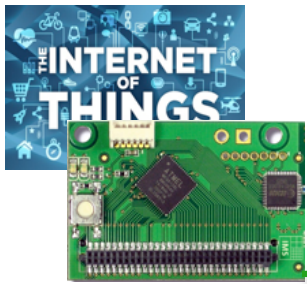


CLEAR CHANNEL ASSESSMENT WITH LoRa



- CCA uses dedicated LoRa's Channel Activity Detection (CAD) as data reception can be done below the noise floor

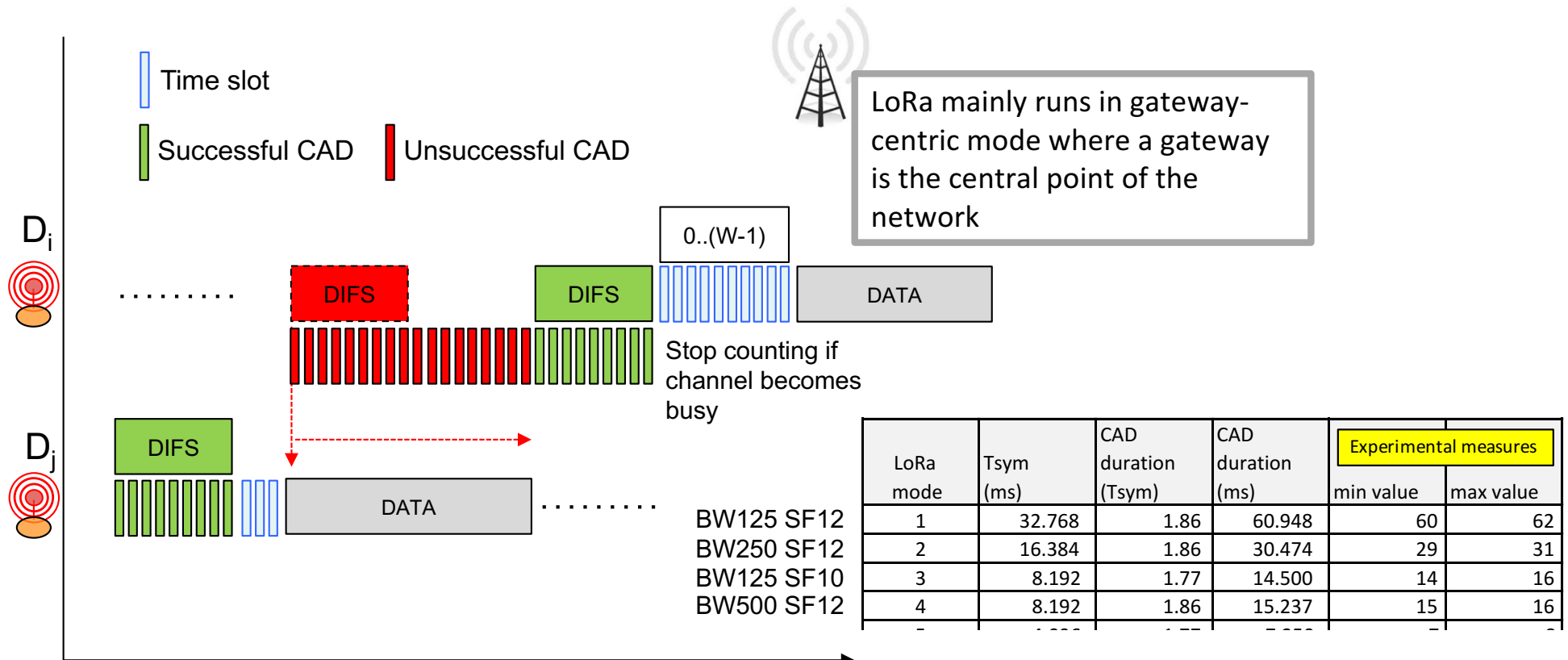




LoRa CSMA DERIVED FROM 802.11



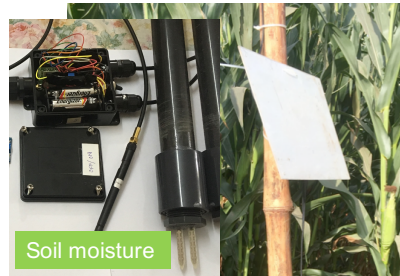
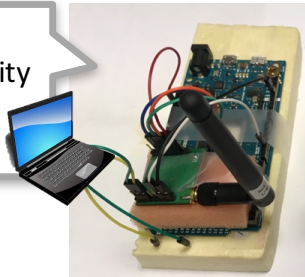
- ❑ CAD duration is between $1.75T_{sym}$ and $2.25T_{sym}$
- ❑ T_{sym} depends on bandwidth & spreading factor
- ❑ SIFS & DIFS are mapped to a number of CAD



EXPERIMENTS ON THE TEST-BED



A node will constantly perform Channel Activity Detection to monitor radio activity



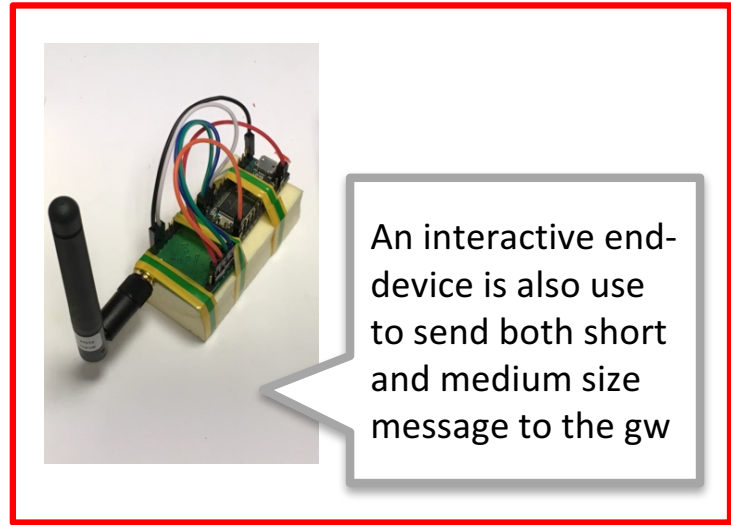
Soil moisture



GPS tracker



Simple sensors will send short messages to the gw



An interactive end-device is also use to send both short and medium size message to the gw

Teensy32 with a uCamI1 camera will be the sources of large image packets to the gw



Photo from EGM

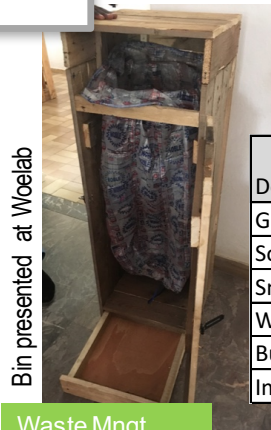
Buoy for water quality

Multi-sensors nodes will send medium size messages to the gw



Weather Station

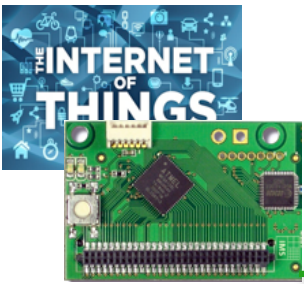
Photo from Unparallel



Bin presented at Woelab

Waste Mngt

Device	QT	Message type	Traffic profile
GPS Tracker	5	small	1 message every 10mins
Soil Moisture	10	small	1 message every 60mins
Smart bin	2	small	1 message every 60mins
Weather Station	1	medium	1 message every 15mins
Buoy	2	medium	1 message every 30mins
Image sensor	3	long	1 image (4-5 packets) every 15 mins



EXPERIMENT 1



```

Sending buoy water data
#####
Packet number 1
Payload size is 40
ToA is w/4B header 2270
--> CarrierSense2: do CAD for DIFS=9CAD
--> DIFS duration 61
###1
--> Channel busy. Retry CAD until free channel
RRRRRRRRRRRRRRRRRRRRRRRRRRRRRRRRRR
--> found busy during 30 CAD
--> wait duration 1891ms
--> retry
--> DIFS duration 547ms
--> counting for 17 CAD
-----
--> found busy during 0
LoRa Sent in 2390ms
LoRa Sent w/CAD in 6231
Packet sent, state 0
  
```



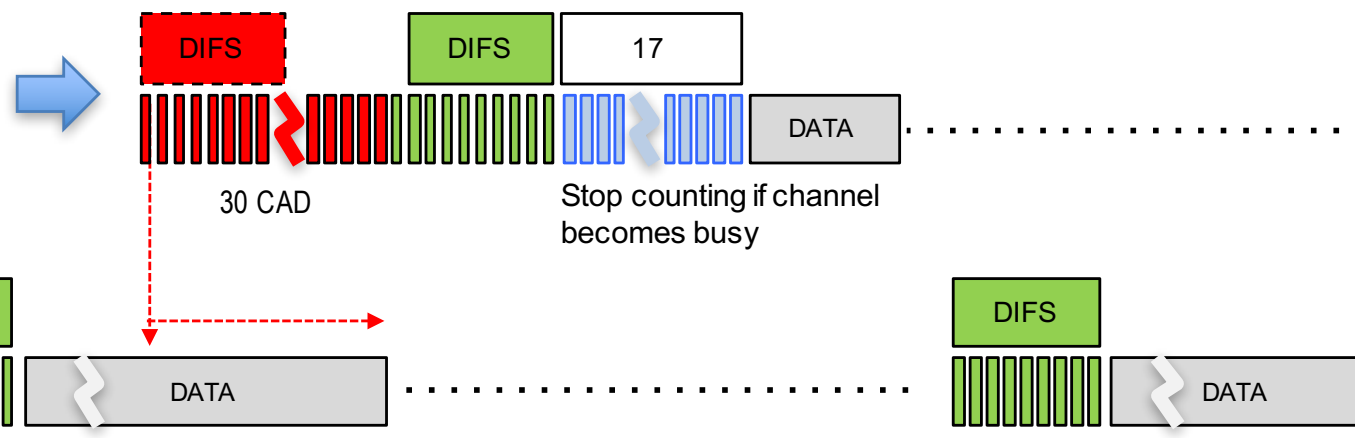
No pkt loss

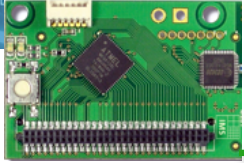


1 pkt lost



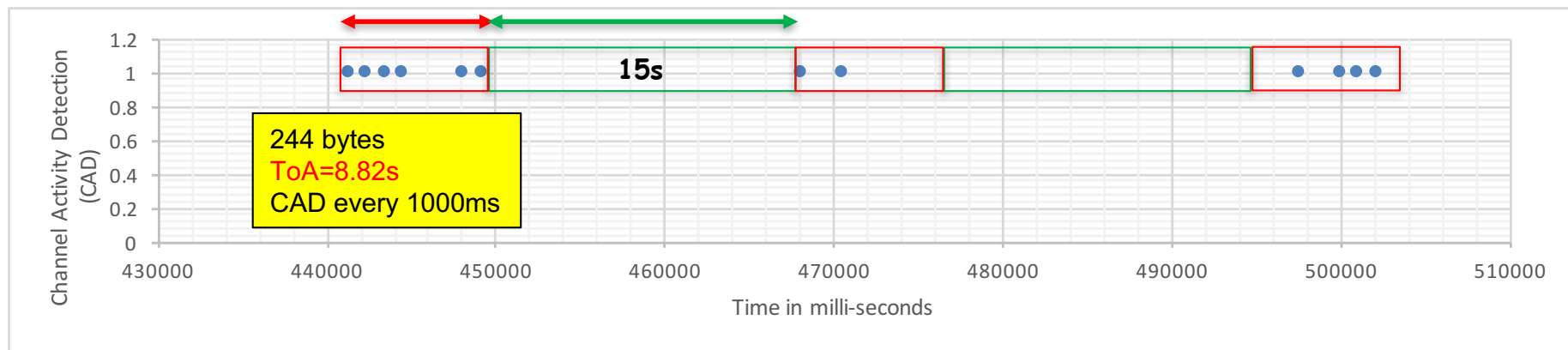
2 pkt lost

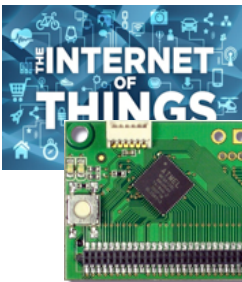




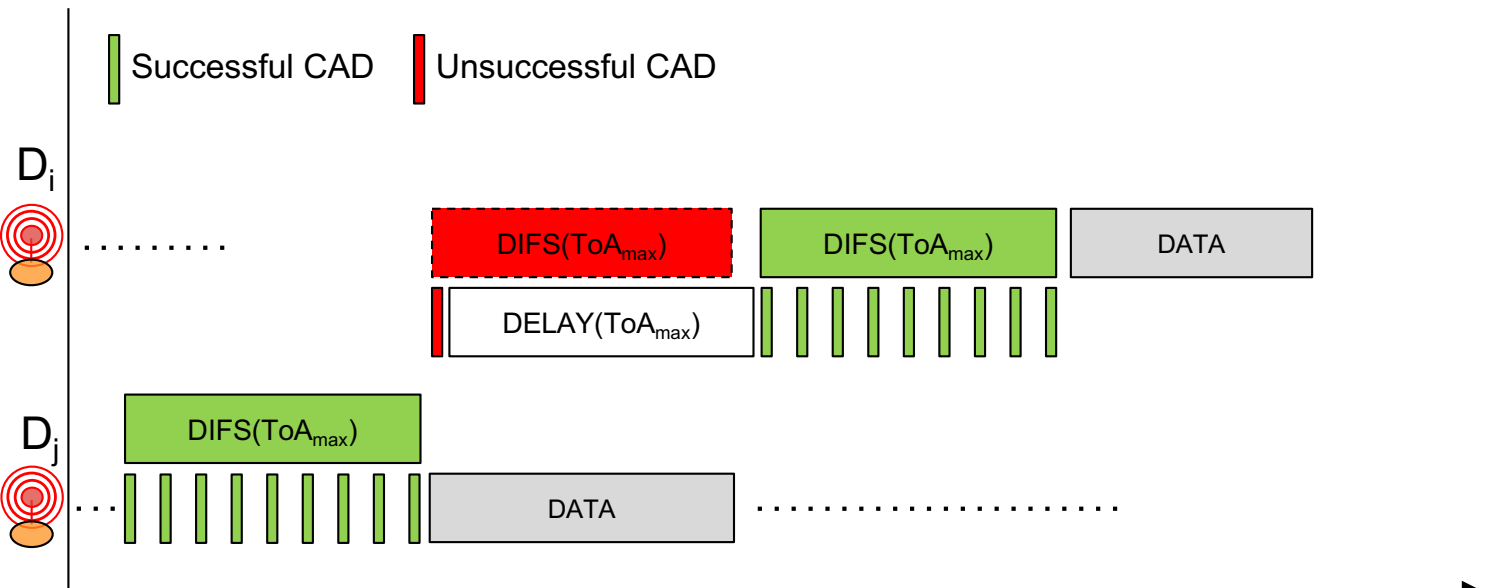
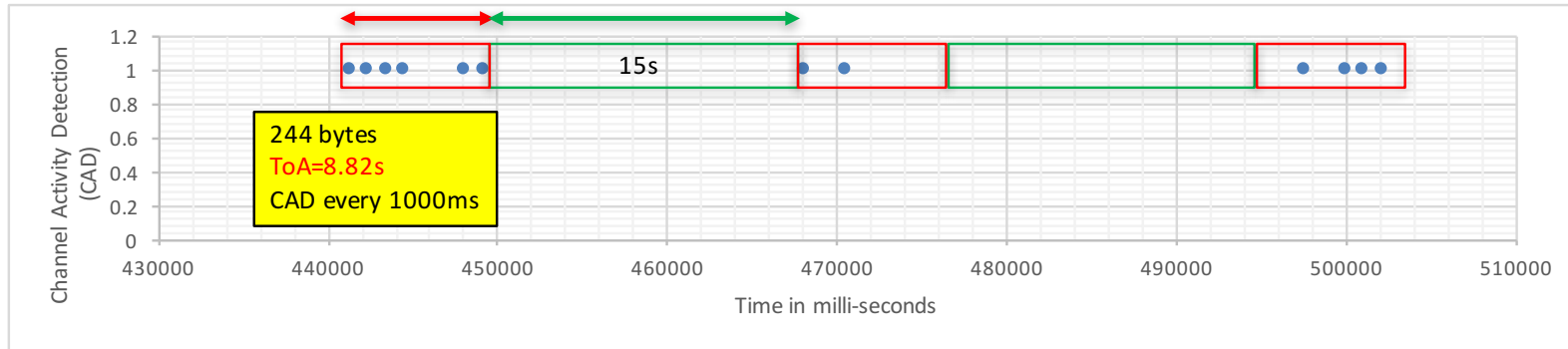
CAD RELIABILITY?

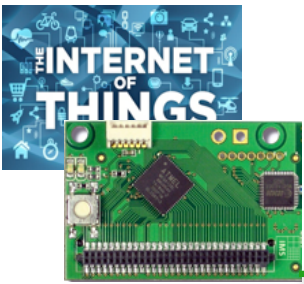
- ❑ CAD reliability decreases as distance increases
 - ❑ A CAD returning false does not mean that there is no activity!
- ❑ During a long transmission (i.e. several seconds), there is usually at least one CAD returning true



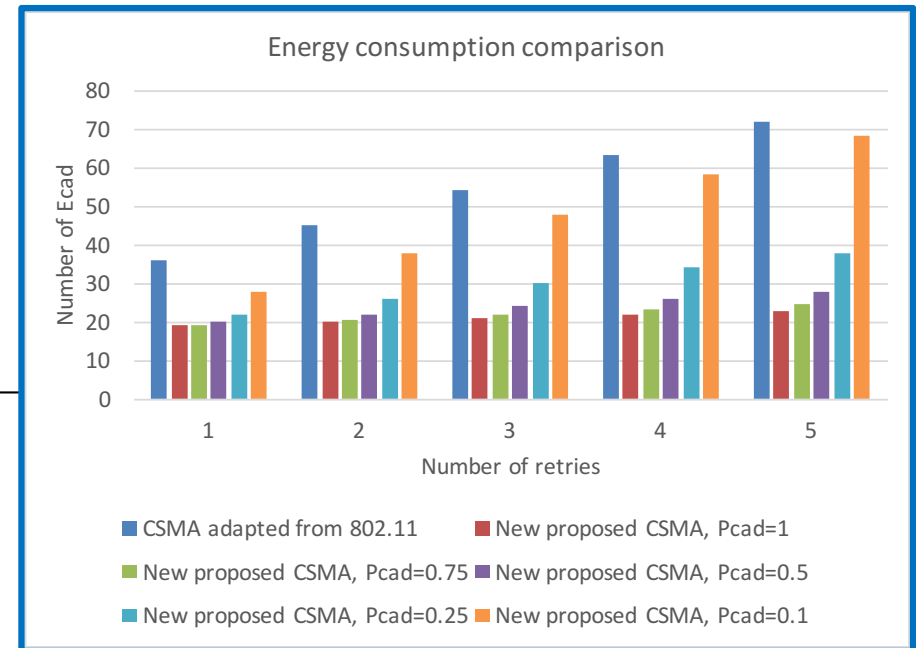
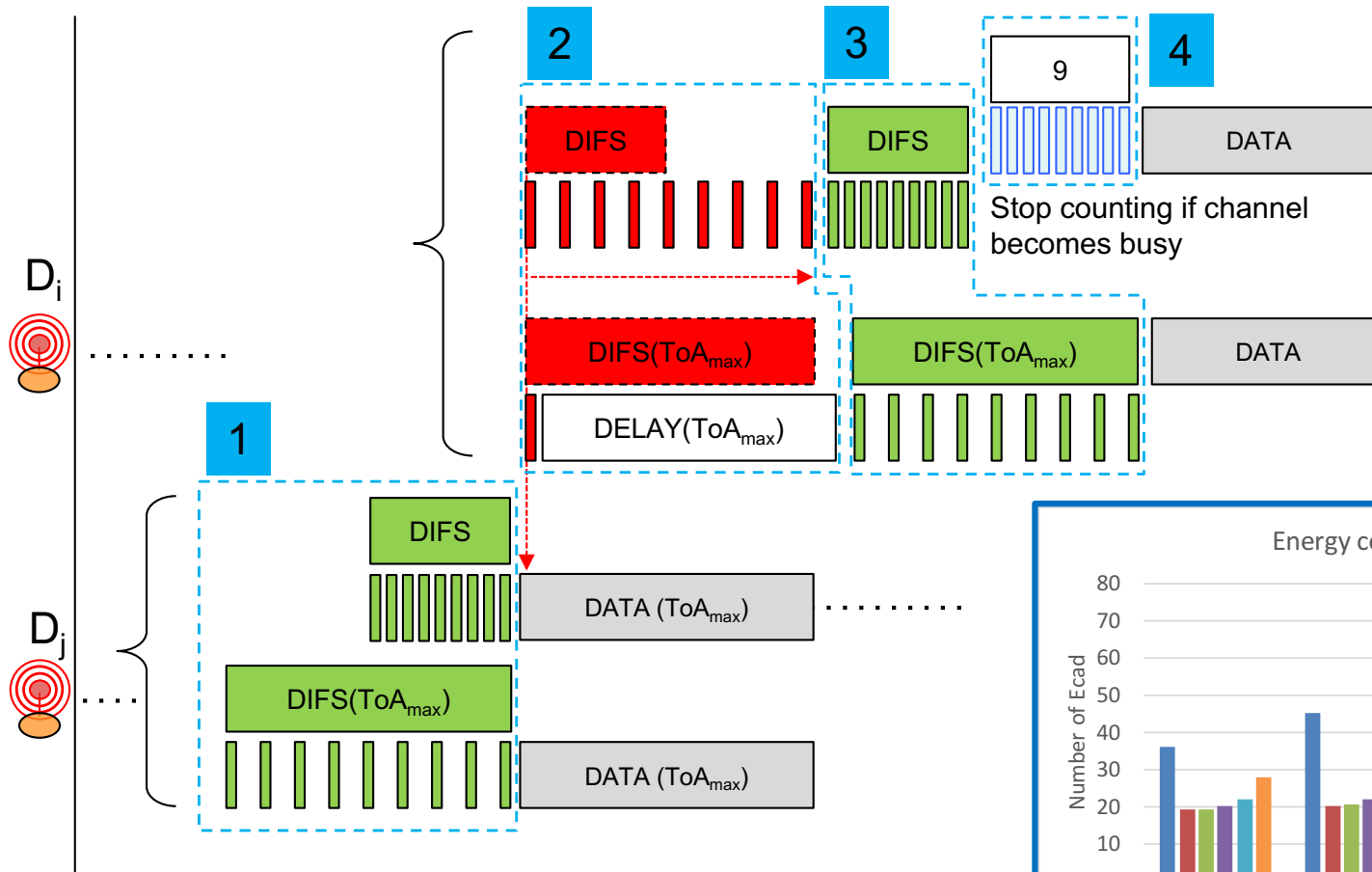


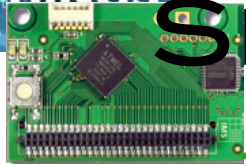
LORA CSMA ADAPTED TO LONGER MSG





CSMA VARIANTS & COMPARISON





SELECT THE CSMA VARIANT

- ❑ Latency depends on maxToA, i.e. max packet length
- ❑ When maxToA is small (only traditional devices)
 - ❑ CSMA derived from 802.11 has lowest latency and is efficiently handling packet collisions
 - ❑ as maxToA is small, vulnerability time is small and...
 - ❑ ...CAD reliability issue has little impact
- ❑ When maxToA is larger (e.g. image sensors)
 - ❑ CAD reliability is a concern
 - ❑ To improve robustness, latency is directly linked to maxToA
 - ❑ **However, it is possible to decrease maxToA by not using the maximum packet size for image packet**
 - ❑ Overhead is 4 bytes per additional packet

LoRa mode	BW	CR	SF	time on air in second for payload size of						max thr. for 255B in bps
				5 bytes	55 bytes	105 bytes	155 Bytes	205 Bytes	255 Bytes	
1	125	4/5	12	0.95846	2.59686	4.23526	5.87366	7.51206	9.15046	223
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